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Stefan Schaffler et al.

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8/20/04

L#	Hits	Search String	Databases
S1	2583	(process near2 control\$3) and (adaptive near2 control\$3)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB
S2	811	S1 and (measure\$4 or collect\$3) with data)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB
S3	495	S1 and (model\$3 with data)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB
S4	300	S2 and S3	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB
S5	155	S4 and ((predict\$3 or forecast\$3) with model\$1)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB
S6	155	S4 and (model\$1 with (accuracy or error\$1))	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB
S7	115	S5 and S6	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB
S8	32	S4 and (model\$3 with regression)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB
S9	48	S4 and ("mean square" with (error or deviation))	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB
S10	0	S4 and (sort\$3 with data with (error or deviation))	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB
S12	178	S4 and (data with (error or deviation))	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB
S14	57	S4 and ((eliminate\$3 or discard\$3) with data)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB
S16	0	S4 and (range with continuous with data)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB
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S21	155	S7 or S8 or S9 or S13 or S15 or S17 or S20	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB
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S13	10	S11 and S12	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB
S15	44	S12 and S14	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB
S17	6	S4 and (range with continuous)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB
S22	49	S4 and (continuous with data)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB
S23	172	S4 and (data with range)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB
S24	36	S22 and S23	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB
S20	12	S18 and S19	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB

09/857281

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Results of search set L21:S7 or S8 or S9 or S13 or S15 or S17 or S20

Document Kind	Codes	Title
US	20040130442 A1	Wireless and powerless sensor and interrogator
US	20040130276 A1	System and method of applying adaptive control to the control of particle accelerators with val
US	20040129838 A1	Flow control device and method of controlling flow
US	20040117040 A1	System and method of adaptive control of processes with varying dynamics
US	20040111168 A1	Adaptive value generating apparatus, adaptive procedure control program, and adaptive valu
US	20040103108 A1	Method and computer-based system for non-probabilistic hypothesis generation and verificatio
US	20040083993 A1	State space control of solenoids
US	20040083013 A1	Method of operating a plant and a control system for controlling the same
US	20040059441 A1	Klin thermal and combustion control
US	20040031058 A1	Method and apparatus for browsing using alternative linkbases
US	20040015335 A1	Method, system and medium for controlling manufacturing process using adaptive models ba:

Issue Date	Current OR	Abstract
20040708	340/443	
20040708	315/501	
20040708	244/199	
20040617	700/29	
20040610	700/28	
20040527	707/100	
20040506	123/90.11	
20040429	700/47	
20040325	700/29	
20040212	725/112	
20040122	703/2	

US 20030229900 A1	Method and apparatus for browsing using multiple coordinated device sets	20031211 725/87
US 20030217337 A1	Method for controlling the performance of a target system	20031120 716/1
US 20030195641 A1	State based adaptive feedforward PID controller	20031016 700/42
US 20030093392 A1	System for intelligent control based on soft computing	20030515 706/13
US 20030088322 A1	Kiln thermal and combustion control	20030508 700/53
US 20030078684 A1	Method and apparatus for modeling dynamic and steady-state processes for prediction, contr	20030424 700/44
US 20030065410 A1	Method and apparatus for controlling a non-linear mill	20030403 700/37
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US 20030049376 A1	Feedback control of sub-atmospheric chemical vapor deposition processes	20030313 427/255.28
US 20030044344 A1	Method for controlling polysulfide production	20030306 423/562
US 20030028265 A1	Kiln/cooler control and upset recovery using a combination of model predictive control and ex	20030206 700/31
US 20030028263 A1	Method and apparatus for adaptive control of marginally stable systems	20030206 700/29
US 20030027424 A1	Feedforward and feedback control for conditioning of chemical mechanical polishing pad	20030206 438/692
US 20030018400 A1	Method and apparatus for creating time-optimal commands for linear systems	20030123 700/29
US 20030018399 A1	Method for optimizing a plant with multiple inputs	20030123 700/28
US 20030014191 A1	System, method and computer program product for identifying chemical compounds having di	20030116 702/19
US 20030014131 A1	Method for optimizing a plant with multiple inputs	20030116 700/29
US 20020197934 A1	Control of chemical mechanical polishing pad conditioner directional velocity to improve pad li	20021226 451/21
US 20020197745 A1	Feedback control of a chemical mechanical polishing device providing manipulation of remov	20021226 438/5
US 20020186660 A1	Adaptive control of data packet size in networks	20021212 370/248
US 20020156542 A1	Methods, devices and systems for monitoring, controlling and optimizing processes	20021024 700/30
US 20020151992 A1	Media recording device with packet data interface	20021017 700/83
US 20020077537 A1	Ferromagnetic foreign body detection with background canceling	20020620 600/409
US 20020072828 A1	Computer method and apparatus for constraining a non-linear approximator of an empirical pr	20020613 700/269
US 20020053555 A1	Spot welding system and method for sensing welding conditions in real time	20020509 219/110
US 20020044014 A1	Amplifier measurement and modeling processes for use in generating predistortion parameter	20020418 330/2
US 20020016665 A1	System for intelligent control of an engine based on soft computing	20020207 701/106
US 20020016640 A1	Multi-variable matrix process control	20020207 700/29
US 20020008578 A1	Amplifier measurement and modeling processes for use in generating predistortion parameter	20020124 330/149
US 20010050592 A1	Amplifier measurement and modeling processes for use in generating predistortion parameter	20011213 330/2
US 20010025232 A1	Hybrid linear-neural network process control	20010927 703/13
US 6757579 B1	Kalman filter state estimation for a manufacturing system	20040629 700/108
US 6757570 B1	System and method for adaptive control of uncertain nonlinear processes	20040629 700/45
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US 6738882 B1	Method and apparatus for scheduling based on state estimation uncertainties	20040518 700/100
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US 6736089 B1	Method and system for sootblowing optimization	20040518 122/379
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US 6571227 B1	Method, system and computer program product for non-linear mapping of multi-dimensional d	20030527 706/15
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US 6505085 B1	Method and apparatus for creating time-optimal commands for linear systems	20030107 700/28
US 6496713 B2	Ferromagnetic foreign body detection with background canceling	20021217 600/409
US 6493596 B1	Method and apparatus for controlling a non-linear mill	20021210 700/37
US 6487459 B1	Method and apparatus for modeling dynamic and steady-state processes for prediction, contri	20021126 700/44
US 6476670 B2	Amplifier measurement and modeling processes for use in generating predistortion parameter	20021105 330/2
US 6463371 B1	System for intelligent control of a vehicle suspension based on soft computing	20021008 701/40
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US 6453246 B1	System, method, and computer program product for representing proximity data in a multi-dirr	20020917 702/27
US 6438430 B1	Kiln thermal and combustion control	20020820 700/28
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US 6400996 B1	Adaptive pattern recognition based control system and method	20020604 700/83
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US 6381504 B1	Method for optimizing a plant with multiple inputs	20020430 700/44
US 6373033 B1	Model-based predictive control of thermal processing	20020416 219/497
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US 6353406 B1	Dual mode tracking system	20020305 342/118
US 6342810 B1	Predistortion amplifier system with separately controllable amplifiers	20020129 330/51
US 6278962 B1	Hybrid linear-neural network process control	20010821 703/13
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US 6207936 B1	Model-based predictive control of thermal processing	20010327 219/497
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US 6144910 A	Vehicle control apparatus and method	20001107 701/50
US 6122557 A	Non-linear model predictive control method for controlling a gas-phase reactor including a rap	20000919 700/45
US 6112126 A	Adaptive object-oriented optimization software system	20000829 700/29
US 6110214 A	Analyzer for modeling and optimizing maintenance operations	20000829 703/2
US 6092919 A	System and method for adaptive control of uncertain nonlinear processes	20000725 700/45
US 6091567 A	Modeling position error nonlinearity to improve servo performance	20000718 360/77.08
US 6054894 A	Digital control of a linc linear power amplifier	20000425 330/149
US 6047221 A	Method for steady-state identification based upon identified dynamics	20000404 700/44
US 6038540 A	System for real-time economic optimizing of manufacturing process control	20000314 705/8
US 6026334 A	Control system for cross-directional profile sheet formation	20000215 700/28
US 6018643 A	Apparatus and method for adaptively forming an antenna beam pattern in a wireless commun	20000125 455/63.4
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US 5933345 A	Method and apparatus for dynamic and steady state modeling over a desired path between tw	19990803 700/44

US 5920478 A	Multi-input multi-output generic non-interacting controller	19990706 700/29
US 5920477 A	Human factored interface incorporating adaptive pattern recognition based controller apparatus	19990706 382/181
US 5908176 A	In-flight adaptive performance optimization (APO) control using redundant control effectors of	19990601 244/203
US 5903454 A	Human-factored interface incorporating adaptive pattern recognition based controller apparatus	19990511 700/83
US 5901552 A	Method of adjusting the air/fuel ratio for an internal combustion engine having a catalytic conv	19990511 60/274
US 5877954 A	Hybrid linear-neural network process control	19990302 700/29
US 5870405 A	Digital transmission of acoustic signals over a noisy communication channel	19990209 714/701
US 5867386 A	Morphological pattern recognition based controller system	19990202 700/83
US 5774357 A	Human factored interface incorporating adaptive pattern recognition based controller apparatus	19980630 713/600
US 5745652 A	Adaptive resource allocation using neural networks	19980428 706/14
US 5714866 A	Method and apparatus for fast battery charging using neural network fuzzy logic based control	19980203 320/152
US 5704012 A	Adaptive resource allocation using neural networks	19971230 706/19
US 5701400 A	Method and apparatus for applying if-then-else rules to data sets in a relational data base and	19971223 706/45
US 5684650 A	Digital servo control system for use in disk drives	19971104 360/77.06
US 5682309 A	Feedback method for controlling non-linear processes	19971028 700/29
US 5680272 A	Digital servo control system for use in disk drives	19971021 360/78.04
US 5677809 A	Digital servo control system for use in disk drives, having state space observer including integ	19971014 360/78.09
US 5675450 A	Digital servo control system for use in disk drives using driver saturation model	19971007 360/78.09
US 5659667 A	Adaptive model predictive process control using neural networks	19970819 706/23
US 5646797 A	Digital servo control system for use in disk drives	19970708 360/75
US 5638230 A	Digital servo control system for use in disk drives	19970610 360/78.04
US 5602889 A	Digital servo control system for use in disk drives, including sample integrity tester for reducin	19970211 360/78.04
US 5586221 A	Predictive control of rolling mills using neural network gauge estimation	19961217 706/23
US 5586033 A	Control system with neural network trained as general and local models	19961217 701/50
US 5555495 A	Method for adaptive control of human-machine systems employing disturbance response	19960910 700/38
US 5519605 A	Model predictive control apparatus and method	19960521 700/31
US 5517511 A	Digital transmission of acoustic signals over a noisy communication channel	19960514 714/755
US 5461559 A	Hierarchical control system for molecular beam epitaxy	19951024 700/29
US 5394322 A	Self-tuning controller that extracts process model characteristics	19950228 700/37
US 5377308 A	Method and system for process control with complex inference mechanism using qualitative a	19941227 706/52
US 5311421 A	Process control method and system for performing control of a controlled system by use of a	19940510 700/37
US 5301101 A	Receding horizon based adaptive control having means for minimizing operating costs	19940405 700/36
US 5282261 A	Neural network process measurement and control	19940125 706/23
US 5251285 A	Method and system for process control with complex inference mechanism using qualitative a	19931005 706/10
US 5249954 A	Integrated imaging sensor/neural network controller for combustion systems	19931005 431/14
US 5051932 A	Method and system for process control with complex inference mechanism	19910924 707/5
US 4929099 A	Multi-line serial printer	19900529 400/76
US 4926309 A	Artificial intelligence for adaptive machining control of surface finish	19900515 700/29
US 4882526 A	Adaptive process control system	19891121 318/561
US 4780744 A	System for quality monitoring and control in an electrophotographic process	19881025 399/39
US 4768143 A	Apparatus and method using adaptive gain scheduling algorithm	19880830 700/37
US 4708459 A	Electrophotographic color proofing apparatus and method	19871124 399/39
US 4639853 A	Time-discrete adaptive switching on-off controller	19870127 700/29
US 4630189 A	System for determining abnormal plant operation based on whiteness indexes	19861216 700/30
US 4491718 A	Template-matching adaptive control system for welding	19850101 219/124.22
US 3631697 A	ROLLING MILL WORKPIECE DELIVERY THICKNESS CONTROL	19720104 72/10.4